

Q1: let g, ∇ be induced metric, connection on M

take $p \in M, v \in T_p M$

let $\gamma = g$ -geodesic

$\bar{\gamma} = \bar{g}$ -geodesic

s.t. $\gamma(0) = \bar{\gamma}(0) = p, \gamma'(0) = \bar{\gamma}'(0) = v$

M tot. geodesic $\Rightarrow \bar{\gamma}$ lies in M

(A)

$$\Rightarrow \bar{\gamma}' \in T_{\bar{\gamma}} M$$

$$\Rightarrow \nabla_{\bar{\gamma}} \bar{\gamma}' = \pi(\bar{\nabla}_{\bar{\gamma}} \bar{\gamma}') = 0$$

$$\Rightarrow \bar{\gamma} = \gamma \text{ by uniqueness of ODEs}$$

$$\Rightarrow \text{every } g\text{-geodesic} = \bar{g}\text{-geodesic} \quad (B)$$

since p, v arbitrary

spec $\gamma = \bar{\gamma}$ $\forall$ choices of p, v (B)

$$\Rightarrow \nabla_{\gamma'(0)} \gamma'(0) = \bar{\nabla}_{\bar{\gamma}'(0)} \bar{\gamma}'(0)$$

$$\Rightarrow B(v, v) = \bar{\nabla}_{\bar{\gamma}'(0)} \bar{\gamma}'(0) - \nabla_{\gamma'(0)} \gamma'(0) = 0 \quad (C)$$

$$\Rightarrow B = 0 \quad \forall p, v$$

$$\text{spec } B = 0 \Rightarrow \bar{\nabla}_{\gamma'} \gamma' = \nabla_{\gamma'} \gamma' + B(\gamma', \gamma') = 0$$

(C)

$$\Rightarrow \gamma = \bar{\gamma} \Rightarrow \bar{\gamma} \text{ lies in } M \Rightarrow M \text{ tot. geodesic} \quad (A)$$

Q2: catenoid: $r = \cosh(z) = \sqrt{x^2 + y^2}$

↳ parametrization: $F(\theta, z) = (\cosh(z) \cos \theta, \cosh(z) \sin \theta, z)$
 $\theta \in [0, 2\pi), z \in \mathbb{R}$

$\Rightarrow \partial_\theta F = (-\cosh(z) \sin \theta, \cosh(z) \cos \theta, 0)$

$\partial_z F = (\sinh(z) \cos \theta, \sinh(z) \sin \theta, 1)$

$\Rightarrow g_{\theta\theta} = \partial_\theta F \cdot \partial_\theta F = \cosh^2(z)$

$g_{\theta z} = \partial_\theta F \cdot \partial_z F = 0$

$g_{zz} = \sinh^2(z) + 1 = \cosh^2(z)$

so $g_{ij} =$

θ	z
$\cosh^2(z)$	0
0	$\cosh^2(z)$

choice of unit normal: $\underline{V} = \frac{(-\cos \theta, -\sin \theta, \sinh(z))}{\sqrt{1 + \sinh^2(z)}}$

scalar second fundamental form in coords: $h_{ij} = \partial_i^2 F \cdot \underline{V}$

$\partial_\theta^2 F = (-\cosh(z) \cos \theta, -\cosh(z) \sin \theta, 0)$

$\partial_{\theta z}^2 F = (-\sinh(z) \sin \theta, \sinh(z) \cos \theta, 0)$

$\partial_{zz}^2 F = (\cosh(z) \cos \theta, \cosh(z) \sin \theta, 0)$

$\Rightarrow h_{\theta\theta} = \partial_\theta^2 F \cdot \underline{V} = \frac{\cosh(z)}{\sqrt{1 + \sinh^2(z)}} = 1, h_{\theta z} = 0, h_{zz} = \frac{-\cosh(z)}{\sqrt{1 + \sinh^2(z)}} = -1$

$$\Rightarrow h^i_j = g^{ip} h_{pj} = \frac{1}{\cosh^2(z)} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\Rightarrow H = \text{Scalar mean curvature}$$

$$= \text{tr}_g h$$

$$= 0$$

Q3: recall Gauss-Bonnet says: if Ω curved polygon in (M, g)

$$\Rightarrow \int_{\Omega} K + \int_{\partial\Omega} k + \sum \varepsilon_i = 2\pi \chi(\Omega)$$

Gauss curvature
geodesic curvature of ∂
exterior angles
Euler characteristic

if Ω geodesic triangle $\Rightarrow \chi = V - E + F$

$$= 3 - 3 + 1$$

$$= 1$$

and $\partial\Omega$ has zero curvature

and $\sum_{\text{ext. angles}} \varepsilon_i = 3\pi - \sum_{\text{interior angles}} \theta_i$

since $K = \text{const}$

$$\Rightarrow K|\Omega| + 3\pi - \sum \theta_i = 2\pi$$

$$\Rightarrow \sum \theta_i = \pi + K|\Omega|$$

Q4.1. we have $[X, Y]_p = \lim_{t \rightarrow 0} \frac{D_{\varphi_t} Y(\varphi_t(p)) - Y(p)}{t}$

$$= \frac{d}{dt} \Big|_{t=0} D_{\varphi_t} Y(\varphi_t(p)) = 0 \quad \forall p$$

now since $\varphi_{s+t} = \varphi_s \circ \varphi_t \Rightarrow D_{\varphi_{s+t}} = D_{\varphi_s} \circ D_{\varphi_t}$

$$\Rightarrow \frac{d}{dt} \Big|_{t=s} D_{\varphi_t} (Y(\varphi_t(p))) = \lim_{t \rightarrow 0} \frac{D_{\varphi_{t+s}} Y(\varphi_{t+s}(p)) - D_{\varphi_s} Y(\varphi_s(p))}{t}$$

$$= D_{\varphi_s} \left(\lim_{t \rightarrow 0} \frac{D_{\varphi_t} Y(\varphi_t(\varphi_s(p))) - Y(\varphi_s(p))}{t} \right)$$

$$= D_{\varphi_s} ([X, Y]_{\varphi_s(p)})$$

$$= 0$$

$$\begin{aligned} \Rightarrow D_{\varphi_t} Y(\varphi_t(p)) &= \text{const in } t \\ &= D_{\varphi_0} Y(\varphi_0(p)) \\ &= Y(p) \end{aligned}$$

$$\Rightarrow D_{\varphi_t} Y|_p = Y|_{\varphi_t(p)}$$

and by same reason, $D_{\varphi_t} X|_p = X|_{\varphi_t(p)}$, $D_{\varphi_t} X|_p = X|_{\varphi_t(p)}$, $D_{\varphi_t} Y|_p = Y|_{\varphi_t(p)}$

Ex. Consider function $F = \varphi_{-t} \circ \varphi_{-s} \circ \varphi_t \circ \varphi_s$

$$\Rightarrow \frac{\partial}{\partial s} F \Big|_p = D\varphi_{-t} Y \Big|_{\varphi_{-s} \circ \varphi_t \circ \varphi_s(p)} + \underbrace{D\varphi_{-t} \circ D\varphi_{-s} \circ D\varphi_t Y \Big|_{\varphi_s(p)}}_{''}$$

$$D\varphi_{-t} \circ D\varphi_{-s} Y \Big|_{\varphi_t \circ \varphi_s}$$

$$= D\varphi_{-t} Y \Big|_{\varphi_{-s} \circ \varphi_t \circ \varphi_s}$$

$$\Rightarrow \frac{\partial}{\partial s} F \Big|_p = 0 \quad \forall t, s, p$$

and similarly $\frac{\partial}{\partial t} F \Big|_p = 0 \quad \Rightarrow \quad \varphi_t \circ \varphi_s = \varphi_s \circ \varphi_t$

Ex define $f_{t,s}(x) = (\varphi_t \circ \varphi_s)(x) \equiv (\varphi_s \circ \varphi_t)(x)$

then $\partial_t f = \partial_t (\varphi_t \circ \varphi_s) = X \Big|_f$

$\partial_s f = \partial_s (\varphi_s \circ \varphi_t) = Y \Big|_f$