

Q1 If $\gamma(t) = \text{curve in } M$ with $\gamma(0) = p$, $\gamma'(0) = X$

then $\frac{d}{dt} \Big|_{t=0} (f \circ \gamma)(\gamma(t)) = X(f \circ \gamma) \Big|_p$

$$\frac{d}{dt} \Big|_{t=0} f(\gamma(\gamma(t))) = (D\varphi|_p X)(f) \Big|_{\varphi(p)} \quad \text{since} \quad \frac{d}{dt} \Big|_{t=0} \gamma(\gamma(t)) = D\varphi|_p X$$

$$= \bar{X}(f) \Big|_{\varphi(p)}$$

and similarly $\gamma(f \circ \varphi) = \bar{\gamma}(f) \Big|_{\varphi(p)}$

we $\bar{X}(\bar{\gamma}(f)) \Big|_q = X(\bar{\gamma}(f \circ \varphi)) \Big|_{\varphi^{-1}(q)}$

$$= X(\gamma(f \circ \varphi)) \Big|_{\varphi^{-1}(q)}$$

$$\Rightarrow [\bar{X}, \bar{\gamma}]f \Big|_q = \bar{X}(\bar{\gamma}f) \Big|_q - \bar{\gamma}(\bar{X}f) \Big|_q$$

$$= X(\gamma(f \circ \varphi)) \Big|_{\varphi^{-1}(q)} - \gamma(X(f \circ \varphi)) \Big|_{\varphi^{-1}(q)}$$

$$= [X, \gamma](f \circ \varphi) \Big|_{\varphi^{-1}(q)}$$

$$= (D\varphi|_{\varphi^{-1}(q)} [X, \gamma])(f) \Big|_q$$

Q1 define $F: \text{End}(V) \rightarrow T^{(1,1)}(V)$

$$\text{by } l \mapsto F_l(v, w) = \omega(l(v))$$

clearly linear

pick basis e_i for V , θ^i for V^* s.t. $\theta^i(e_j) = \delta_{ij}$

if $l(v^i e_j) = l_j^i v^j$

$$\text{then } F_l = l_j^i \theta^j \otimes e_i$$

$\Rightarrow F = \text{bijective} \Rightarrow \text{linear isomorphism}$

Q2: let's show: $T \in T^{(1,1)}(M) \Leftrightarrow T: \mathfrak{X}(M) \otimes \mathfrak{X}^*(M) \rightarrow C^\infty(M)$
smooth, linear over $C^\infty(M)$

general case is verification

\Rightarrow trivial since in coords $T = T_i^j dx^i \otimes \partial_j$

$$\Rightarrow T(fX, g\omega) = f X^i g \omega_j T_i^j$$
$$= f g T(X, \omega)$$

for $X \in \mathfrak{X}(M)$, $f, g \in C^\infty(M)$
 $\omega \in \mathfrak{X}^*(M)$

\Leftarrow in coords we have $T(X^i \partial_i, \omega_j dx^j)$

$$= X^i \omega_j T(\partial_i, dx^j)$$
$$= \underbrace{(T(\partial_i, dx^j) dx^i \otimes \partial_j)}_{= (1,1)\text{-tensor}}(X, \omega)$$

Q3: by chain rule, $dx^i = \frac{\partial x^i}{\partial y^a} dy^a$

$$\frac{\partial}{\partial x^k} = \frac{\partial y^c}{\partial x^k} \frac{\partial}{\partial y^c}$$

$$\Rightarrow A_{ij}^k dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k}$$

$$= A_{ij}^k \underbrace{\frac{\partial x^i}{\partial y^a} \frac{\partial x^j}{\partial y^b} \frac{\partial y^c}{\partial x^k}}_{= A_{ab}^c} dy^a \otimes dy^b \otimes \frac{\partial}{\partial y^c}$$

$$= A_{ab}^c$$

$$(\text{tr } A)_b^a = A_{ab}^a = A_{ij}^k \frac{\partial x^i}{\partial y^a} \frac{\partial y^a}{\partial x^k} \frac{\partial x^j}{\partial y^b} = A_{ij}^i \frac{\partial x^j}{\partial y^b} = (\text{tr } A)_j \frac{\partial x^j}{\partial y^b}$$

by chain rule $\frac{\partial x^i}{\partial x^k} = \delta_{ik}$

Q2: recall general property about n -forms on \mathbb{R}^n :

If $e_1, \dots, e_n = \text{std basis}$, $\omega^1, \dots, \omega^n = \text{dual basis}$

$$\Rightarrow (\omega^1 \wedge \dots \wedge \omega^n)(v_1, \dots, v_n) = \det \begin{vmatrix} | & | & \dots & | \\ v_1 & v_2 & \dots & v_n \\ | & | & \dots & | \end{vmatrix}$$

let $E_p = \text{oriented, } g\text{-ON basis of } T_p M$

$\theta^i = \text{dual basis}$

$$\Rightarrow dV|_p = \theta^1 \wedge \dots \wedge \theta^n$$

If x^i coords near $p \Rightarrow \partial_i = a_i^j E_j$

$$\Rightarrow dV(\partial_1, \dots, \partial_n) = \det \begin{vmatrix} | & | & \dots & | \\ a_1^1 & a_1^2 & \dots & a_1^n \\ | & | & \dots & | \end{vmatrix}$$
$$= \det A \quad \text{for } A_{ij} := a_j^i$$

$$\text{new } g_{ij} = g(\partial_i, \partial_j) = a_i^p a_j^q g(e_p, e_q)$$

$$= a_i^p a_j^q \delta_{pq}$$

$$= a_i^p a_j^p = (A^T A)_{ij}$$

$$\Rightarrow \det(g_{ij}) = |\det A|^2$$

$$\Rightarrow \det A = \sqrt{\det(g_{ij})} \quad \text{since } \partial_i \text{ positively-oriented} \\ (\text{so } \det A > 0)$$

$$\Rightarrow dV = \det A dx^1 \wedge \dots \wedge dx^n = \sqrt{\det(g_{ij})} dx^1 \wedge \dots \wedge dx^n$$